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# Instantaneous frequency analysis of broadband LFM signals by photonics-assisted equivalent frequency sampling

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We propose a photonics-assisted equivalent frequency sampling (EFS) method to analyze the instantaneous frequency of broadband linearly frequency modulated (LFM) microwave signals. The proposed EFS method is implemented by a photonic scanning receiver, which is operated with a frequency scanning rate slightly different from the repetition rate of the LFM signals. Compared with the broadband LFM signal analysis based on temporal sampling, the proposed method avoids the use of high-speed analog to digital converters, and the instantaneous frequency acquisition realized by frequency-to-time mapping is also simplified since real-time Fourier transformation is not required. Feasibility of the proposed method is verified through an experiment, in which frequency analysis of K $\alpha$ -band LFM signals with a bandwidth up to 3 GHz is demonstrated with a moderate sampling rate of 100 MSa/s. The proposed method is highly demanded for analyzing the instantaneous frequency of broadband LFM signals used in radar and electronic warfare systems.

**Keywords:** frequency measurement; equivalent frequency sampling; microwave photonics. **DOI:** 10.3788/COL202119.013901

# 1. Introduction

Linearly frequency modulated (LFM) microwave signals have wide applications in radar and electronic warfare systems<sup>[1-3]</sup>.</sup> As the rapid development of broadband radar and electronic warfare systems, frequency analysis of LFM signals having a large instantaneous bandwidth is becoming more and more challenging. The commercial electrical spectral analyzer (ESA) usually has a frequency scanning rate that is considerably lower than the frequency modulation speed of the LFM signals used in radar and electronic warfare applications, which makes it impossible to measure the instantaneous frequency of broadband LFM signals. A commonly used method for instantaneous frequency analysis is implemented by temporally sampling the broadband LFM signals with a high-speed analog-to-digital converter (ADC), which, however, leads to a very high cost and sometimes suffers from an insufficient sampling rate. To relax the requirement for high-speed ADCs, an equivalent temporal sampling technique with low-speed ADCs can be applied<sup>[4]</sup>, which is implemented by sampling multiple periods of the signal under test (SUT) with a sampling rate slightly different from the repetition rate of the SUT. Meanwhile, further signal processing such as short-time Fourier transformation (STFT) is still required to get the instantaneous frequency of the SUT, which takes a lot of computations.

In recent years, many photonics-assisted methods have been proposed for microwave frequency measurement. In such systems, frequency measurement is implemented by mapping the frequency to a parameter such as amplitude, time, phase sloop, and space [5-12]. Thanks to the ultra-large operation bandwidth of photonic technologies, these methods can measure signals in a large spectral range. However, most of the photonic microwave frequency measurement methods are not suitable for broadband instantaneous frequency analysis because they can only measure single-frequency signals. One photonic method having the ability of instantaneous frequency measurement is the real-time Fourier transformation (RTFT) realized by time stretching in a dispersive medium<sup>[13,14]</sup>. This method is far from practical applications, because it suffers from a small measurement time window, and the measurement resolution is limited to the gigahertz (GHz) level<sup>[14]</sup>.

In this Letter, we propose and demonstrate a photonicsassisted equivalent frequency sampling (EFS) method to analyze the instantaneous frequency of broadband LFM signals. This method uses our recently proposed photonic scanning receiver<sup>[10,15,16]</sup>, which is realized by optical-domain frequency scanning and electrical-domain intermediate frequency (IF) envelope detection. Based on this photonic scanning receiver, which can scan a wide spectral range at a very fast speed, the EFS is achieved by setting its frequency scanning rate slightly different from the repetition rate of the LFM-SUT. The main advantage of this method is that it avoids the use of high-speed ADCs. Besides, the instantaneous frequency to be measured is mapped to the time position of a short pulse; thus, the instantaneous frequency acquisition is greatly simplified compared with the time-domain STFT processing. Furthermore, the photonic scanning receiver uses a photonic frequency multiplication technique, making it possible to achieve a large frequency measurement range.

## 2. Principle

Figure 1(a) shows the schematic diagram of the photonic-scanning-receiver-based frequency measurement system. A laser diode (LD) generates a continuous wave (CW) light, which is modulated by a Mach–Zehnder modulator (MZM1). MZM1 is driven by an IF-band LFM signal (IF-LFM) generated by a low-speed electrical signal generator (ESG). MZM1 is biased at its maximum transmission point to suppress the odd-order modulation sidebands such that the  $\pm 2^{nd}$ -order modulation sidebands are generated in the optical spectrum. An erbiumdoped fiber amplifier (EDFA1) is used to boost the optical power of the signal from MZM1, and an optical dual-band filter (ODBF) is followed to select the  $\pm 2^{nd}$ -order modulation sidebands. The obtained optical signal (at point *a*) can be expressed as

$$E_1(t) \propto J_2(\alpha) \left[ e^{j2\pi (f_c + 2f_{\rm LFM})t} + e^{j2\pi (f_c - 2f_{\rm LFM})t} \right],\tag{1}$$

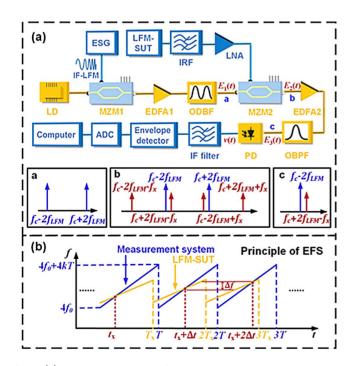


Fig. 1. (a) Schematic diagram of the photonic-scanning-receiver-based microwave photonic frequency measurement system and (b) principle of the EFS.

where  $J_2(\cdot)$  is the second-order Bessel function of the first kind,  $\alpha$  is the modulation index of MZM1,  $f_c$  is the frequency of the CW light, and  $f_{\text{LFM}} = f_0 + kt$  is the instantaneous frequency of the IF-LFM signal in a single period ( $0 < t \le T$ ) with T,  $f_0$ , and k being the temporal period, the initial frequency, and the chirp rate, respectively. To avoid spectral aliasing between adjacent modulation sidebands after MZM1,  $2(f_0 + kT) \le 4f_0$  should be satisfied, requiring  $kT \le f_0$ .

Then, the optical signal from the ODBF is modulated by another MZM (MZM2), which is driven by the LFM-SUT. Before being applied to MZM2, the LFM-SUT passes through an image-reject filter (IRF) and is amplified by a low-noise amplifier (LNA). The IRF is used to avoid the measurement ambiguity between two frequency bands that mirror each other<sup>[15]</sup>. The obtained optical signal after MZM2 (at point *b*) can be expressed as

$$E_{2}(t) \propto J_{0}(\beta)J_{2}(\alpha) \Big[ e^{j2\pi(f_{c}+2f_{\rm LFM})t} + e^{j2\pi(f_{c}-2f_{\rm LFM})t} \Big] + J_{1}(\beta)J_{2}(\alpha) \Big[ e^{j2\pi(f_{c}+2f_{\rm LFM}+f_{x})t} + e^{j2\pi(f_{c}+2f_{\rm LFM}-f_{x})t} \Big] + J_{1}(\beta)J_{2}(\alpha) \Big[ e^{j2\pi(f_{c}-2f_{\rm LFM}+f_{x})t} + e^{j2\pi(f_{c}-2f_{\rm LFM}-f_{x})t} \Big], \quad (2)$$

where  $J_n(\cdot)$  is the *n*<sup>th</sup>-order (n = 0, 1, and 2) Bessel function of the first kind,  $\beta$  is the modulation index of MZM2, and  $f_x$  is the frequency to be measured. Here, MZM2 is biased at the quadrature point, and only the ±1<sup>st</sup>-order modulation sidebands are considered.

After MZM2, another EDFA (EDFA2) is used to compensate for the optical power loss. Within the expected frequency measurement range of the proposed system, the  $-1^{\text{st}}$ -order sideband at  $f_c + 2f_{\text{LFM}} - f_x$  is close to the optical carrier at  $f_c - 2f_{\text{LFM}}$ , and they are selected out by an optical bandpass filter (OBPF). The obtained optical signal (at point *c*) is

$$E_{3}(t) \propto J_{0}(\beta)J_{2}(\alpha) \left[ e^{j2\pi(f_{c}-2f_{\rm LFM})t} \right] + J_{1}(\beta)J_{2}(\alpha) \left[ e^{j2\pi(f_{c}+2f_{\rm LFM}-f_{x})t} \right].$$
(3)

This optical signal is sent to a photodetector (PD) to perform optical-to-electrical conversion. The generated electrical signal is

$$v(t) \propto dc + J_2 2(\alpha) J_0(\beta) J_1(\beta) \cos[2\pi (4f_{LFM} - f_x)t].$$
 (4)

As can be seen, the obtained electrical signal contains a direct-current (dc) component and a frequency component at  $|4f_{\rm LFM} - f_x|$ . Next, a narrow-band IF filter is used to select the frequency component at  $f_{\rm IF}$ . A microwave envelope detector is followed to get the envelope signal of this IF signal, which can be expressed by<sup>[15]</sup>

$$e(t) \propto \delta(|4f_0 + 4kt - f_x| - f_{\rm IF}) \\ \propto \begin{cases} A(f_x) & t = \frac{f_x + f_{\rm IF} - 4f_0}{4k} \text{ or } \frac{f_x - f_{\rm IF} - 4f_0}{4k}, \\ 0 & \text{else} \end{cases},$$
(5)

where  $A(f_x)$  is the instantaneous non-zero amplitude proportional to the power of the frequency component at  $f_x$ . Based on Eq. (5),  $f_x$  can be estimated by

$$f_x = 4f_0 + 4kt_x - f_{\rm IF}$$
 or  $4f_0 + 4kt_x + f_{\rm IF}$ , (6)

where  $t_x$  is the time when  $e(t) \neq 0$ . From Eq. (6), the frequency to be measured is mapped to the time position. By sampling the envelope signal with an ADC and finding out the time positions corresponding to non-zero amplitudes, the frequency of the SUT can be estimated based on Eq. (6). Here, the frequency acquisition is obviously simplified compared with the signal analysis based on temporal sampling. It should be noted that, the frequency to be measured should be located in  $[4f_0 - f_{\rm IE}]$  $4f_0 - f_{IF} + 4kT$ ] or  $[4f_0 + f_{IF}, 4f_0 + f_{IF} + 4kT]$ . To avoid overlapping between the two spectral ranges,  $2kT \leq f_{IF}$  should be satisfied. To eliminate the frequency measurement ambiguity between the two spectral ranges, an IRF is used in Fig. 1(a). The maximum frequency measurement range of this method is 4kT, which is four times the bandwidth of the IF-LFM signal. In our previous demonstrations, this system achieved good performance in measuring single-frequency signals and slowly varying signals<sup>[15,16]</sup>, while, for high-speed frequency modulated signals from radar and electronic warfare systems, a singlefrequency scanning using the proposed system cannot acquire the complete frequency information of the LFM-SUT. To cope with this problem, we propose the EFS method, of which the principle is as follows.

Assume that the instantaneous frequency of the LFM-SUT is  $f_x = f_1 + k_x t \ (0 < t \le T_x)$ , where  $T_x, f_1$ , and  $k_x$  are the temporal period, the initial frequency, and the chirp rate, respectively. To implement the EFS, the temporal period of the IF-LFM signal (T) is slightly different from  $T_x$ , and the frequency sweeping rate (4k) is different from  $k_x$ . With this configuration, only a specific instantaneous frequency is acquired in a single period of the LFM-SUT. The principle of EFS when T is slightly larger than  $T_x$  is illustrated in Fig. 1(b), where the two straight lines corresponding to the frequency-time relationship of the frequency measurement system and the LFM-SUT have one intersection point in each period. Since both the temporal periods and chirp rates of the two straight lines are different, the vertical coordinates corresponding to the intersection points in different periods are also different, which compose the instantaneous frequency measurement result of the EFS method. The frequency measurement step between two adjacent periods is calculated to be

$$\Delta f = 4k \frac{k_x \tau}{4k - k_x},\tag{7}$$

in which  $\tau = T - T_x$ . The total number of measurement periods required to complete the EFS of the LFM-SUT is

$$m = \left\lceil \frac{k_x T_x}{\Delta f} \right\rceil = \left\lceil T_x \frac{4k - k_x}{4k\tau} \right\rceil,\tag{8}$$

where  $\lceil \cdot \rceil$  is the ceil rounding function. As can be seen, by reducing the value of  $\tau$ , the frequency measurement step is also reduced, and thus more frequency sampling points can be achieved, which is helpful in acquiring the complete frequency

information of the LFM-SUT. Meanwhile, the total measurement time is increased at the same time.

#### 3. Experiment

To investigate the performance of the proposed EFS method, a proof-of-concept experiment is carried out. In the experiment, the CW light generated by the LD (TeraXion Inc.) has a wavelength of 1550.54 nm. The IF-LFM signal generated by the ESG (Keysight M8195S) has a bandwidth of 2.5 GHz (5-7.5 GHz) and a repetition rate of 100 kHz. Both of the MZMs (Fujitsu, FTM7938EZ) have a bandwidth of ~25 GHz. The optical signals from two MZMs are amplified by two EDFAs (Amonics, AEDFA-PA-35-B-FA), respectively. The ODBF is realized by an optical signal processer (Finisar Inc., WaveShaper 4000s), and the OBPF is realized by an optical filter (Yenista, XTM-50). The PD has a 3 dB bandwidth of 10 GHz, and the IF filter is centered at 10 GHz with a 3 dB bandwidth of 15 MHz. The optical spectra at different points are analyzed using an optical spectrum analyzer (Yokogawa, AQ6370C) with a resolution of 0.02 nm. The microwave envelope detector (Agilent, 8474C) has an operation bandwidth from dc to 33 GHz. The envelope signal is sampled by a real-time oscilloscope (Agilent, DSO-X 92504A) with a moderate sampling rate that is 100 MSa/s. Since the image frequency interference is not considered, the IRF is not used in the experiment. Based on these parameters, the frequency measurement range of the established system is chosen to be 30-40 GHz, which is four times the bandwidth of the IF-LFM signal. The time required for a single-period frequency scanning is 10 µs.

To test the measurement accuracy over the whole measurement range, the SUT is set to a single-frequency signal from 30 GHz to 40 GHz with a step of 500 MHz, which is generated by a microwave signal generator (Agilent, E8257D). The optical spectra of the signal after MZM1 and the signal from the ODBF are shown in Fig. 2(a), in which the  $\pm 2^{nd}$ -order modulation sidebands are successfully selected after the ODBF with the undesired components well suppressed. Figure 2(b) shows the spectra of the signal from MZM2 and the signal from the OBPF. It is found that the desired optical carrier and the  $-1^{st}$ -order modulation sideband are acquired after the OBPF. When the frequency of the SUT is 31 GHz, the sampled envelope signal having a single short pulse is shown in Fig. 3. The full width at half-maximum (FWHM) of the pulse is 46 ns, corresponding to a frequency measurement resolution of 46 MHz<sup>[15]</sup>. The averaged measurement error considering all the frequencies is 6.9 MHz. Hence, the proposed system is capable of implementing frequency measurements with small errors over the whole frequency measurement range. Based on the method in Ref. [10], the spurious free dynamic range (SFDR) of the system is measured to be 50 dB.

Then, frequency analysis of LFM signals is demonstrated. Theoretically, the maximum bandwidth of the LFM-SUT that can be measured by the established system is 10 GHz (30–40 GHz). In the experiment, the LFM-SUT is first set to

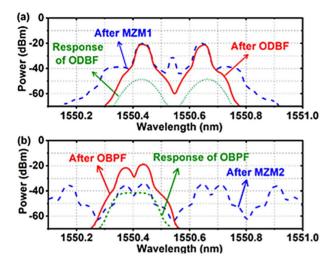


Fig. 2. (a) Optical spectra of the signal after MZM1 and the signal after ODBF and (b) optical spectra of the signal after MZM2 and the signal after OBPF.

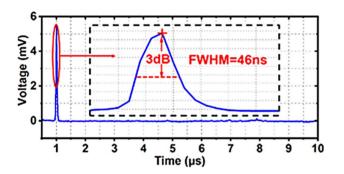


Fig. 3. Sampled waveform of the envelope signal when the SUT is a singlefrequency signal at 31 GHz.

have a positive frequency chirp with a total bandwidth of 3 GHz (30-33 GHz) and a temporal period of 9.5 us. According to Eqs. (7) and (8), the frequency measurement step of the EFS method is 231 MHz, and it takes 13 periods to complete the frequency measurement. As an example, the waveforms of the envelope signals sampled in the 3<sup>rd</sup>, 6<sup>th</sup>, 9<sup>th</sup>, and 12<sup>th</sup> periods are shown in Fig. 4(a). In these waveforms, a short pulse appears at a specific time position, which is 0.58 µs, 1.28 µs, 1.97 µs, and 2.66 µs, respectively. Based on Eq. (6), the instantaneous frequencies acquired in these four periods are 30.58 GHz, 31.28 GHz, 31.97 GHz, and 32.66 GHz, respectively. By reconstructing all of the EFS results into a single period of 9.5 µs, the instantaneous frequency measurement result is finally obtained, as shown in Fig. 4(b), where the true frequency-time relation of the LFM-SUT is also provided. In Fig. 4(b), the averaged measurement error of all 13 frequency sampling results is calculated to be 6.1 MHz.

The previous measurement has a large frequency step because of the relatively large difference between the temporal periods of the frequency scanning receiver and the LFM-SUT, which can only acquire a sparse frequency-time relation. To get more

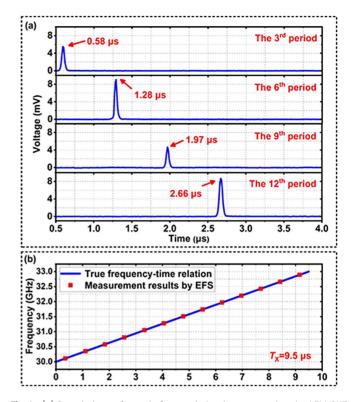


Fig. 4. (a) Sampled waveforms in four periods when measuring the LFM-SUT from 30 GHz to 33 GHz and (b) the measurement results obtained by the proposed method.

complete frequency information, a small frequency measurement step is preferred. To check this property, the temporal period of the LFM-SUT is changed to 9.75 µs ( $\tau = 0.25$  µs) and 9.9 µs ( $\tau = 0.1$  µs), respectively, while the bandwidth remains at 3 GHz (30–33 GHz). The corresponding frequency measurement step is reduced to 111 MHz and 43.5 MHz, respectively. Figure 5 shows the measured frequency-time relations, in which the EFS generates 28 and 69 frequency samples, respectively. In Figs. 5(a) and 5(b), the averaged frequency measurement error is calculated to be 6.3 MHz and 3.3 MHz, respectively. These results can verify that, by reducing the frequency measurement step, the proposed method can obtain very detailed frequency-time information of the LFM-SUT.

In the previous demonstration, the LFM-SUT has a full duty cycle, and its chirp rate is positive. In fact, the proposed EFS method is also capable of analyzing pulsed LFM signals or LFM signals with negative frequency chirps. To show this property, the LFM-SUT is set to a pulsed LFM signal with a negative chirp rate. Specifically, the LFM-SUT has a bandwidth of 3.2 GHz (35.7–32.5 GHz) and a temporal period of 12  $\mu$ s with a duty cycle of 64%. To measure this signal, the scanning period of the IF-LFM signal is tuned to 12.5  $\mu$ s, and the sampling rate of the ADC is still 100 MSa/s. Figure 6 shows the measurement result, which contains 24 EFS values with a step of ~137 MHz. The averaged measurement error is calculated to be 2.4 MHz, and the acquired frequencies take up 7.6  $\mu$ s out of a period of 12  $\mu$ s, which agrees well with the true duty cycle.

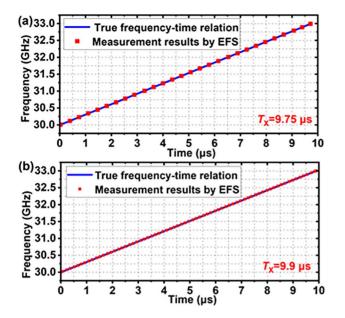


Fig. 5. Measurement results when the temporal period of the LFM-SUT is (a) 9.75  $\mu s$  and (b) 9.9  $\mu s.$ 

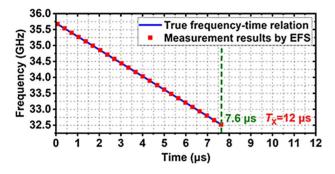


Fig. 6. Measurement results of the pulsed LFM-SUT with a negative chirp rate.

# 4. Conclusion

In conclusion, we have proposed and demonstrated a photonicsassisted EFS method for instantaneous frequency analysis of broadband microwave LFM signals. This method is realized by a photonic scanning receiver that has a frequency scanning rate slightly different from the repetition rate of the LFM-SUT. This method can avoid the use of high-speed ADCs and simplify the frequency acquisition procedure. In the experiment, frequency analysis of K $\alpha$ -band LFM signals with bandwidth up to 3 GHz is implemented with a sampling rate of 100 MSa/s. The averaged instantaneous frequency measurement errors are less than 6.5 MHz. Therefore, the proposed method is a good solution to instantaneous frequency measurement of high-frequency and broadband LFM signals.

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